### A 3D ANALYTICAL MODEL FOR LINEAR ROCK CUTTING PROCESS

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# Introduction

Dredging: sand, clay and/or rock

'Mining sediment from sea floor, transport and dump it'



Sand	Clay	Rock	
Loose particles	Loose particles	Bonded grains	
0.06mm <d<2mm< td=""><td>D&lt;0,06mm</td><td>D&gt;25cm</td></d<2mm<>	D<0,06mm	D>25cm	

- Hard to predict cutting forces
  - Energy consumption
  - Dredging method

http://escape.sg



https://beeldbank.rws.nl/



# Introduction

• Dredging: how?



https://www.royalihc.com

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https://www.royalihc.com

#### Let's see how rock cutting force is calculated



#### Failure modes



Cutting of rock, Vlasblom (2007)

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- The Evans Model (Tensile crack)
  - Sharp tool
  - 2D process
  - Brittle tensile  $\rightarrow \sigma_t$  (=BTS)

$$\rightarrow \beta$$
 = crack angle (Tensile)





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 $F_{c} = \sigma_{T} \cdot h_{i} \cdot w \cdot \frac{2 \cdot \sin(\alpha + \delta)}{1 - \sin(\alpha + \delta)}$ 

DSCRCM, Miedema (2014)

- The Nishimatsu Model (Shear crack)
  - Sharp tool
  - 2D process
  - Brittle shear  $\rightarrow c$



$$F_{h} = \frac{1}{(n+1)} \cdot \frac{c \cdot h_{i} \cdot w \cdot \cos(\phi) \cdot \sin(\alpha + \delta)}{\sin(\beta) \cdot \sin(\alpha + \beta + \delta + \phi)}$$
$$F_{v} = \frac{1}{(n+1)} \cdot \frac{c \cdot h_{i} \cdot w \cdot \cos(\phi) \cdot \cos(\alpha + \delta)}{\sin(\beta) \cdot \sin(\alpha + \beta + \delta + \phi)}$$



DSCRCM, Miedema (2014)

- The Tear/Chip Model
  - Sharp tool
  - 2D process
  - Brittle shear  $\rightarrow c$





DSCRCM, Miedema (2014)

- The Flow Model
  - Sharp tool crushing the surface
  - 2D process
  - Ductile  $\rightarrow c$





$$F_{h} = \frac{\lambda \cdot c \cdot h_{i} \cdot w \cdot cos(\varphi) \cdot sin(\alpha + \delta)}{sin(\beta) \cdot sin(\alpha + \beta + \delta + \varphi)}$$
$$F_{v} = \frac{\lambda \cdot c \cdot h_{i} \cdot w \cdot cos(\varphi) \cdot cos(\alpha + \delta)}{sin(\beta) \cdot sin(\alpha + \beta + \delta + \varphi)}$$

Merchant (1945)

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DSCRCM, Miedema (2014)

# How good is the prediction?

- We can do some experiments
- Dredging: rock cutting with multiple rotating cutting teeth
  - Difficult: start from the beginning
    - Single pick point
    - Linear cutting



# **Research Procedure**

- Determine rock characteristics
- Conduct linear cutting experiments
- Validate existing calculation models
- Improve the calculation models



# **Rock characteristics**

- Sandstone
- 210x53x12 cm





# Uniaxial compression tests





# Uniaxial compression tests



 $\sigma = F/A$  $\sigma_{max} = UCS$ 

 $UCS1_1 = 26.7 \text{ MPa}$  $UCS1_2 = 25.7 \text{ MPa}$  $UCS1_3 = 27.3 \text{ MPa}$ 

Average: UCS1 = 26.6 MPa

#### **Brazilian Tensile tests**



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#### **Brazilian Tensile tests**



 $\sigma = (2*F)/(\pi*D*L)$  $\sigma_{max} = BTS$ 

 $BTS1_1 = 1.2 MPa$  $BTS1_2 = 1.7 MPa$  $BTS1_3 = 1.3 MPa$ 

Average: BTS1 = 1.4 MPa



# **Hoek-Brown Failure Criterion**

• Internal friction angle ( $\varphi$ ')  $\phi' = \sin^{-1} \left( \frac{6am_b(s+m_b\sigma_{3n})^{a-1}}{2(1+a)(2+a)+6am_b(s+m_b\sigma'_{3n})^{a-1}} \right)$ 

• External friction angle (
$$\delta'$$
)  
 $\delta' = \frac{2}{3}\phi'$ 

• Cohesion (c')  

$$c' = \frac{\sigma_{ci}((a+2a)s + (1-a)m_b\sigma_{3n})(s+m_b\sigma_{3n})^{a-1}}{(1+a)(2+a)\sqrt{\frac{a+(6am_b(s+m_b\sigma_{3n})^{a-1}}{(1+a)(2+a)}}}$$



## **Rock characteristics**

Sample	UCS MPa	BTS MPa	m <sub>i</sub> [-]	c' MPa	<b>¢'</b> °	${\delta' \atop \circ}$
1	18.9	1.7	11	3.7	44	29
2	26.6	1.1	24	4.7	52	35
3*	20.4	1.7	12	4.0	45	30
4	17.6	1.3	14	3.3	46	31
5	18.7	1.6	12	3.6	45	30

 $m_i < 9$  ductile failure  $9 < m_i < 15$  brittle-ductile transition  $m_i > 15$  brittle failure





#### Test setup



The pickpoint has a total length of 30cm, with a tip angle of 26°.



# Test setup

- Settings:
  - Cutting angles
    - 40-70 degrees
  - Cutting speed
    - 5 cm/s
  - Depths
    - 0.5-1.5cm
    - (Limited by sensor)
  - Without water
    - No cavitation
    - No hyperbaric conditions



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# Determine failure mode

Failure mode:

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- Brittle or ductile?
  - No plastic deformation  $\rightarrow$  brittle
- Tensile or shear?
  - Insufficient depth for tensile crack → shear
- Nishimatu or Tear/Chip?
  - Tear model limited with cutting angles  $\rightarrow$  Nishimatsu



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### The Nishimatsu Model

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#### Nishimatsu vs. Measurements





# Measured cutting forces are 10~20 times of the Nishimatsu calculations

# 'Is the Nishimatsu model limited by its assumptions?'

- Assume model is correct, but limited by:
  - Sharp tool assumption
  - 2D assumption



• Measured force = Model + bluntness effect + 3D effect

Blunt tool → secondary crushed zone





Zhantao Li (2012)

'P2 is equal to dynamic friction'



#### Dynamic friction



General:  $F_n = W$   $F_{fric} = F_n * \mu$ This case:  $W = F_v$  (experimentation)

This case:  $W = F_v$  (experiment)  $F_n = F_v$   $\mu=0.39$  $F_{fric} = F_v^* 0.39$ 



## The Bluntness effect

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Force to remove secondary crushed zone converges over depth

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#### 2D assumption









• However...





- 3D problem
  - Larger shear area





- 3D problem
  - Measure area from samples







# The outbreaking shear effect



A – the ourbreaking shear surface area

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Quadratically increasing the shear component

#### Combination of the three components



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# Conclusions

- Proposed component model
  - Increases accuracy
  - Sharp tool + 2D assumption limiting factors
  - Still not perfect...
    - Vertical forces still inaccurate



# Conclusions

- Maximum forces linear over depth
  - Linear model component
  - Converging indentation component
  - Quadratically increasing shear component



### Recommendations

- Conduct indentation tests
  - To get more real stress level in the crushed zone
- More experiments to enable the component model into a mature prediction model
- Try to get a cutting process which is dominated by indentation forces (check force over depth)
- Try to get a cutting process which is dominated by shear forces (check force over depth)



# Thank you

